

# **Lecture 3:**

# **Processes & Threads**

# Agenda

## PART 1: Processes

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3.2 Process Parts

3.3 Process States

3.4 Process Control Block (PCB)

3.5 CPU Switch From Process to Process

3.6 Process Scheduling Queues

3.7 Operations on Processes

3.8 Inter-process Communication

# Agenda

## PART 2: Threads

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3.10 Multithreaded Server Architecture Example

3.11 Multithreading Benefits

3.12 Multi-Processor Systems

3.13 Concurrency vs. Parallelism

3.14 Amdahl's Law

# General Definition of a Process?



A process is an activity, or series of activities,  
that converts an input, to an output,  
by doing work.

# **PART 1**

## **Processes**

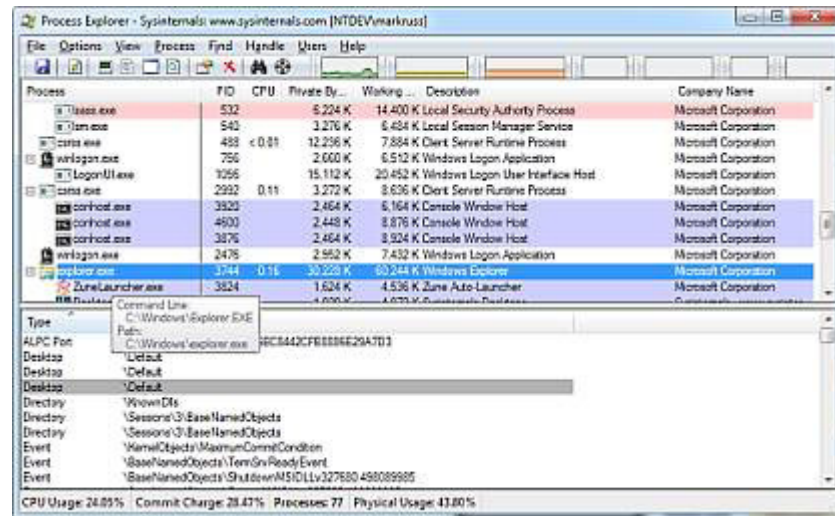
## 3.1 Process Concept in OS

- **Process** – is an active program in execution; process execution must progress in sequential fashion
- Program is a *passive* entity stored on disk (**executable file**), and it becomes a process when executable file is loaded into memory
- One program can be executed multiple times generating multiple processes

# Practical Case

## Process Explorer (Freeware)

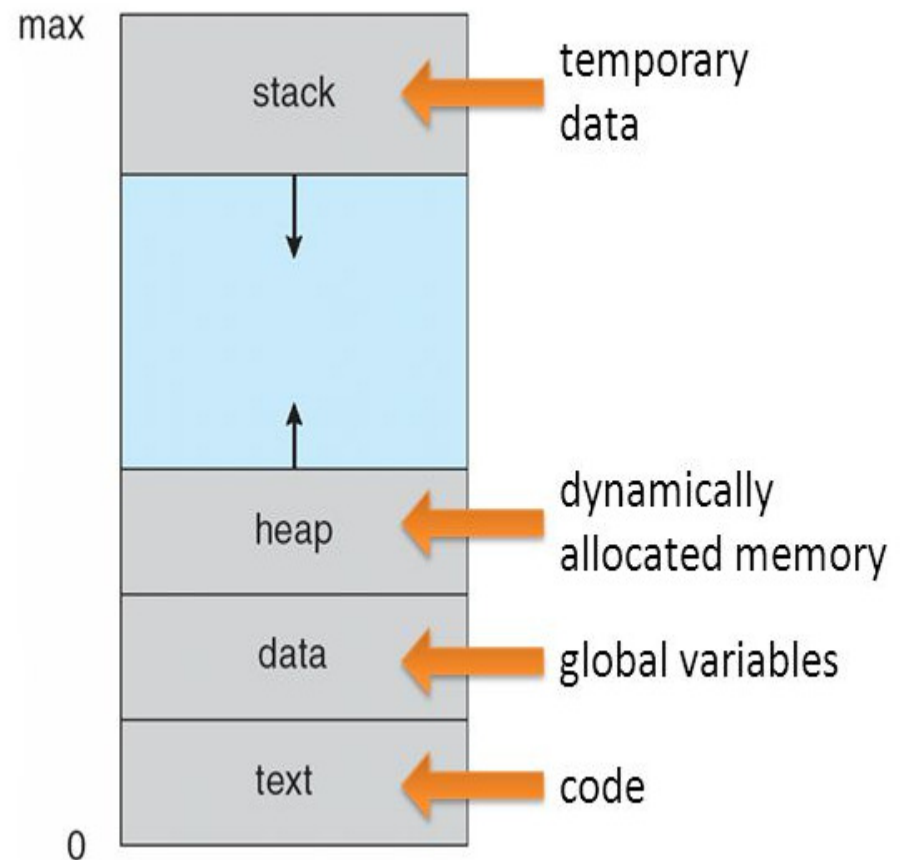
- It is a freeware shows a list of the currently active processes,
- In DLL mode you'll see the DLLs and memory-mapped files that the process has loaded.
- It is useful for tracking down DLL problems and provide insight into the way Windows and applications work.



## 3.2 Process Parts

- **Text Section** containing the program code.
- **Data section** containing global variables
- **Stack** containing function parameters, return addresses, and local variables.
- **Heap** containing memory dynamically allocated during run time.

### A Process in Memory

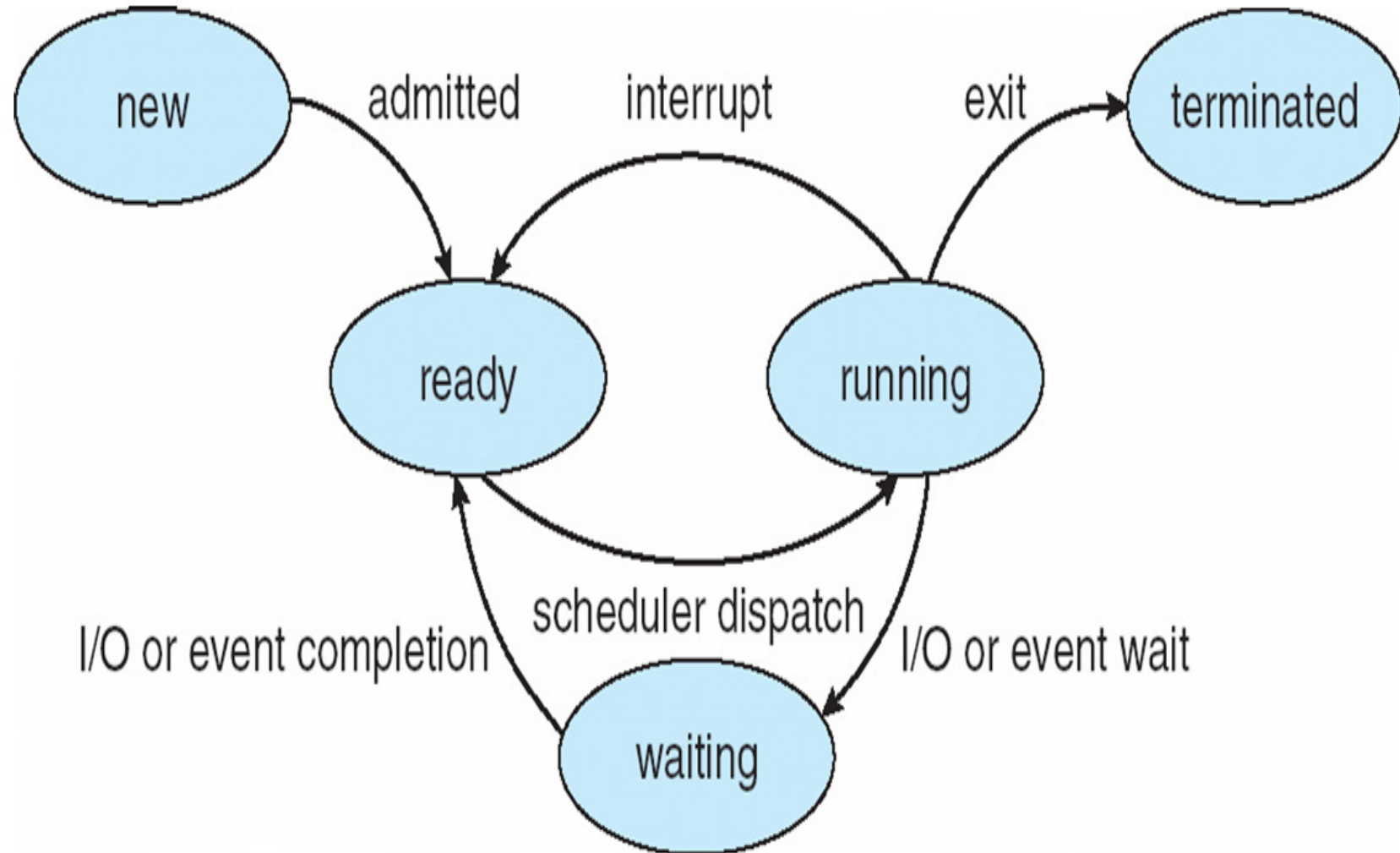




## 3.3 Process States

- As a process executes, it changes **state** to below five states
  - **new**: The process is being created
  - **running**: Instructions are being executed
  - **waiting**: The process is waiting for some event to occur
  - **ready**: The process is waiting to be assigned to a processor
  - **terminated**: The process has finished execution

# Diagram of Process States



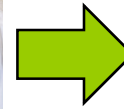
# Analogy CPU vs. Doctor (not required in the exam)



Process 1



Process 2



Process 3

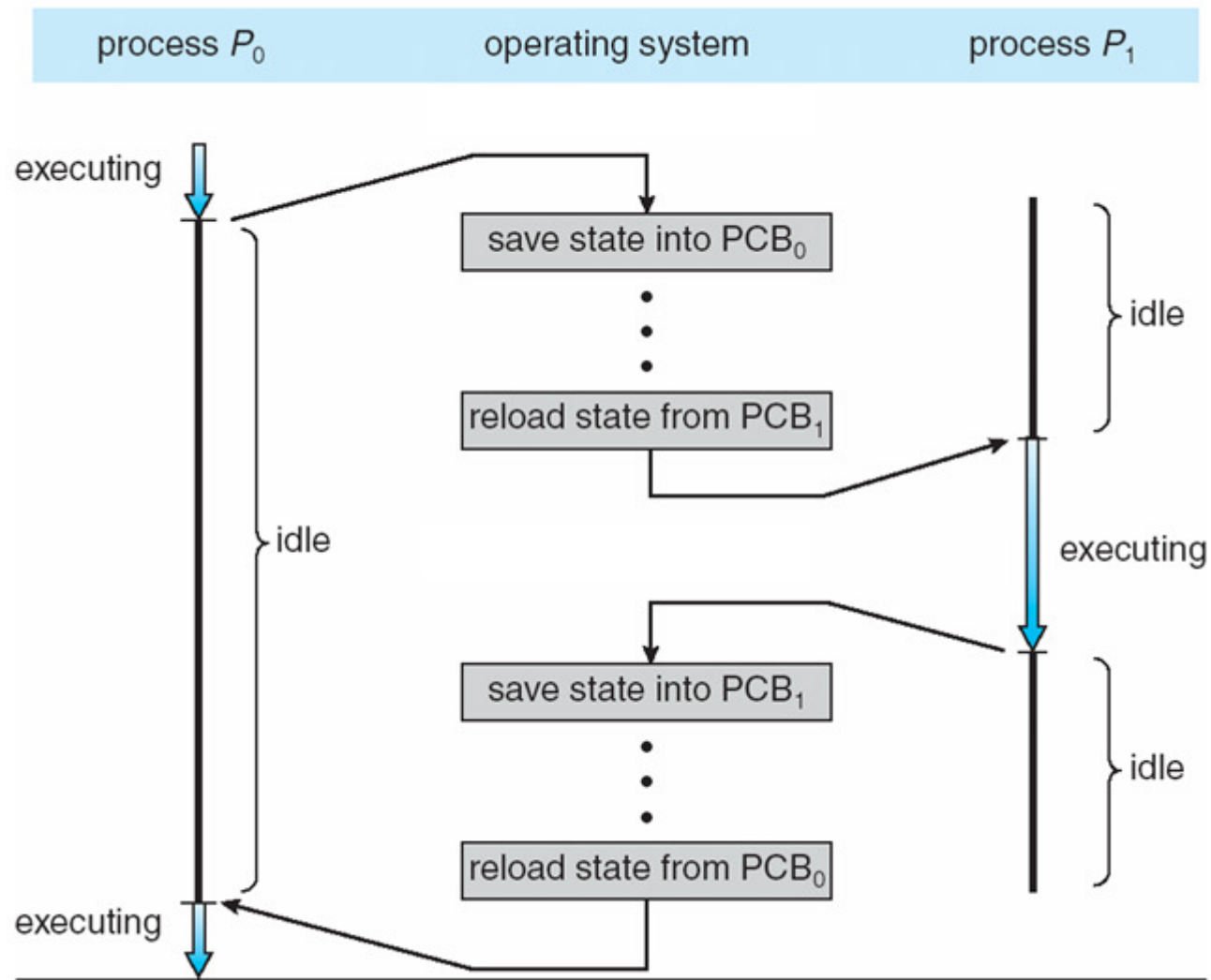


## 3.4 Process Control Block (PCB)

Is the Information associated with each process

- Process state
- Program counter – location of instruction to next execute
- CPU registers
- CPU scheduling information- priorities, scheduling queue pointers
- Memory-management information – memory allocated to the process
- Accounting information – CPU used, clock time elapsed since start, and time limits
- I/O status information – I/O devices allocated to process, and list of open files

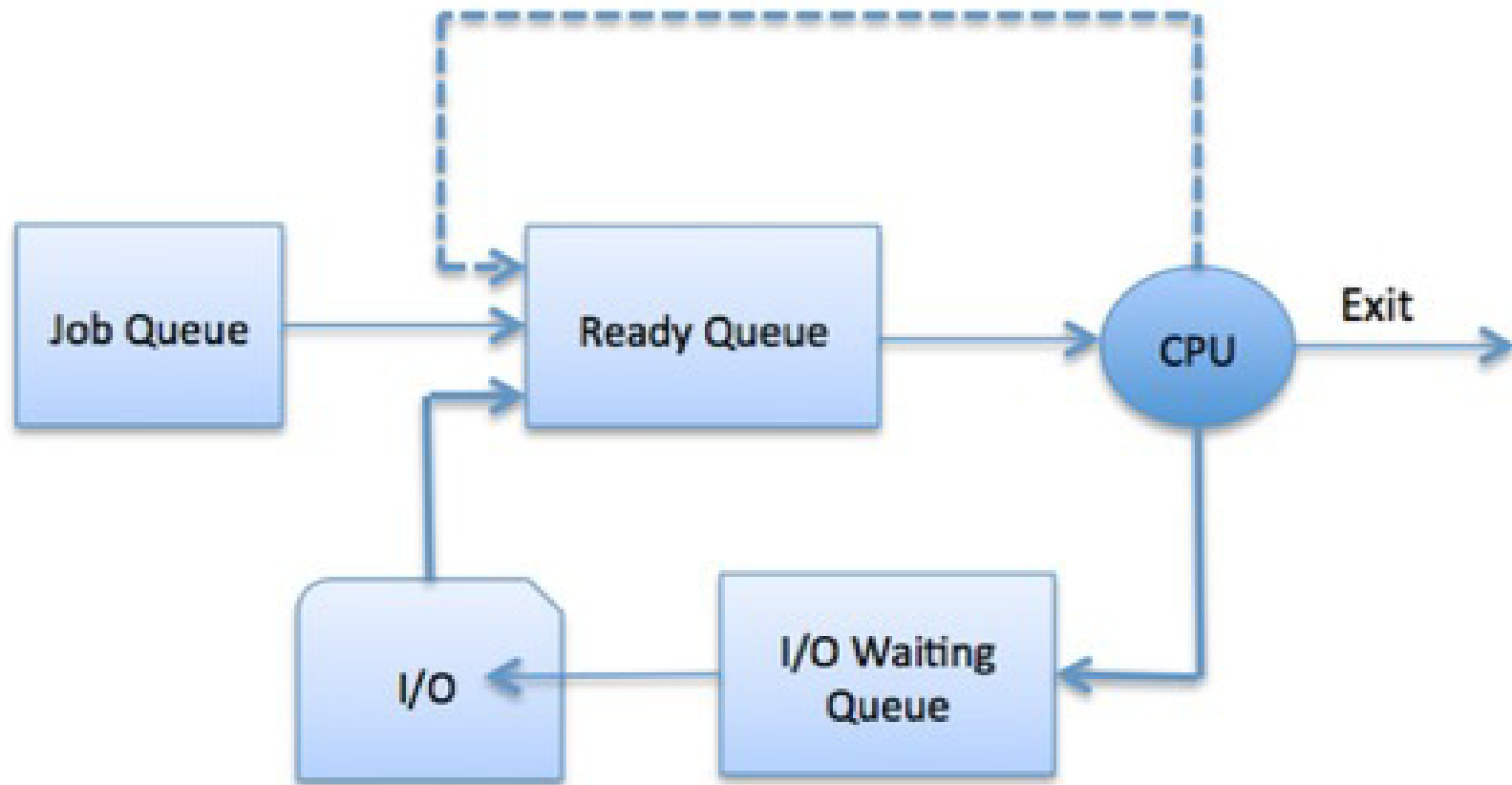
## 3.5 CPU Switch From Process to Process



## 3.6 Process Scheduling Queues

- **Process scheduler** selects among available processes for next execution on CPU
- Maintains **scheduling queues** of processes
  - **Job queue** – set of all processes in the system
  - **Ready queue** – set of all processes residing in main memory, ready and waiting to execute
  - **Device queues** – set of processes waiting for an I/O device
  - Processes migrate among the various queues

# Process Scheduling Queues Diagram



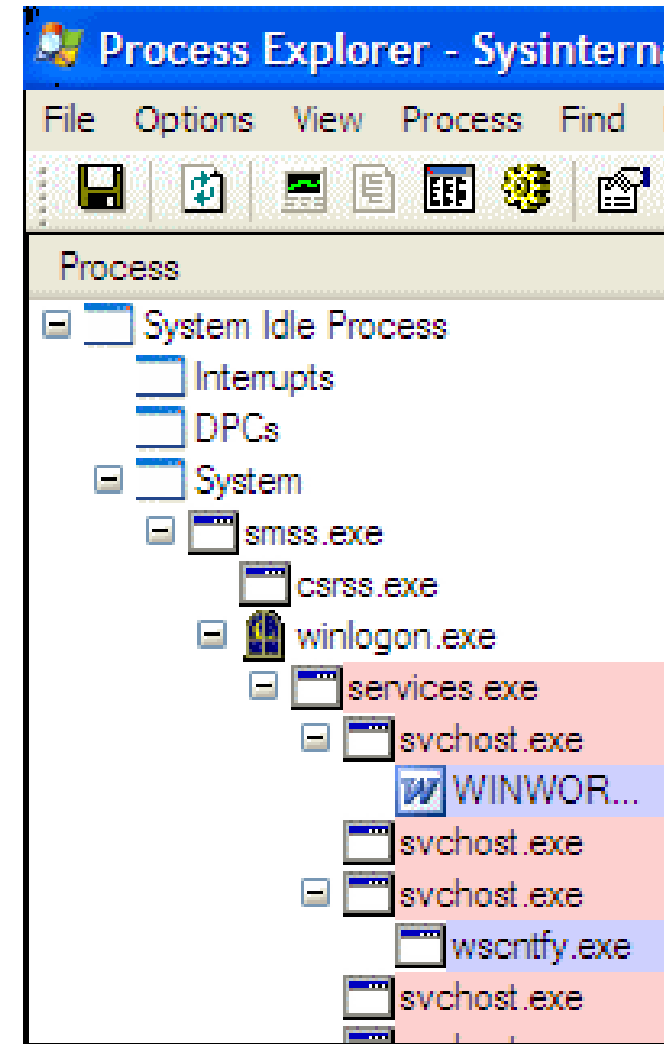
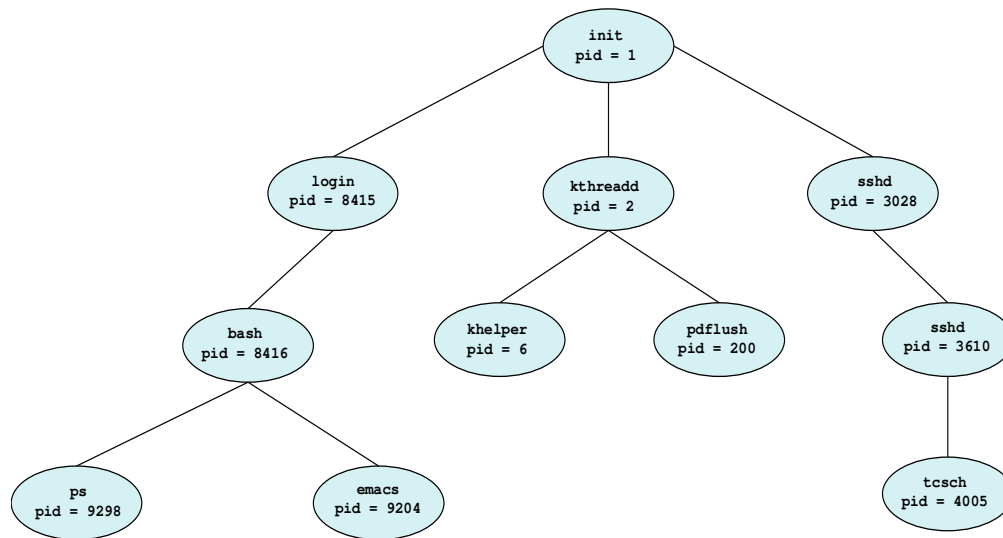
## 3.7 Operations on Processes

### 1) Process Creation

- **Parent** process create **children** processes, which, in turn create other processes, forming a **tree** of processes
- Generally, process identified and managed via a **process identifier (pid)**
- Resource sharing options:
  1. Parent and children share all resources
  2. Children share subset of parent's resources
  3. Parent and child share no resources
- Execution options:
  1. Parent and children execute concurrently
  2. Parent waits until children terminate



# Examples of Tree of Processes (not required in the exam)



## 2. Process Termination

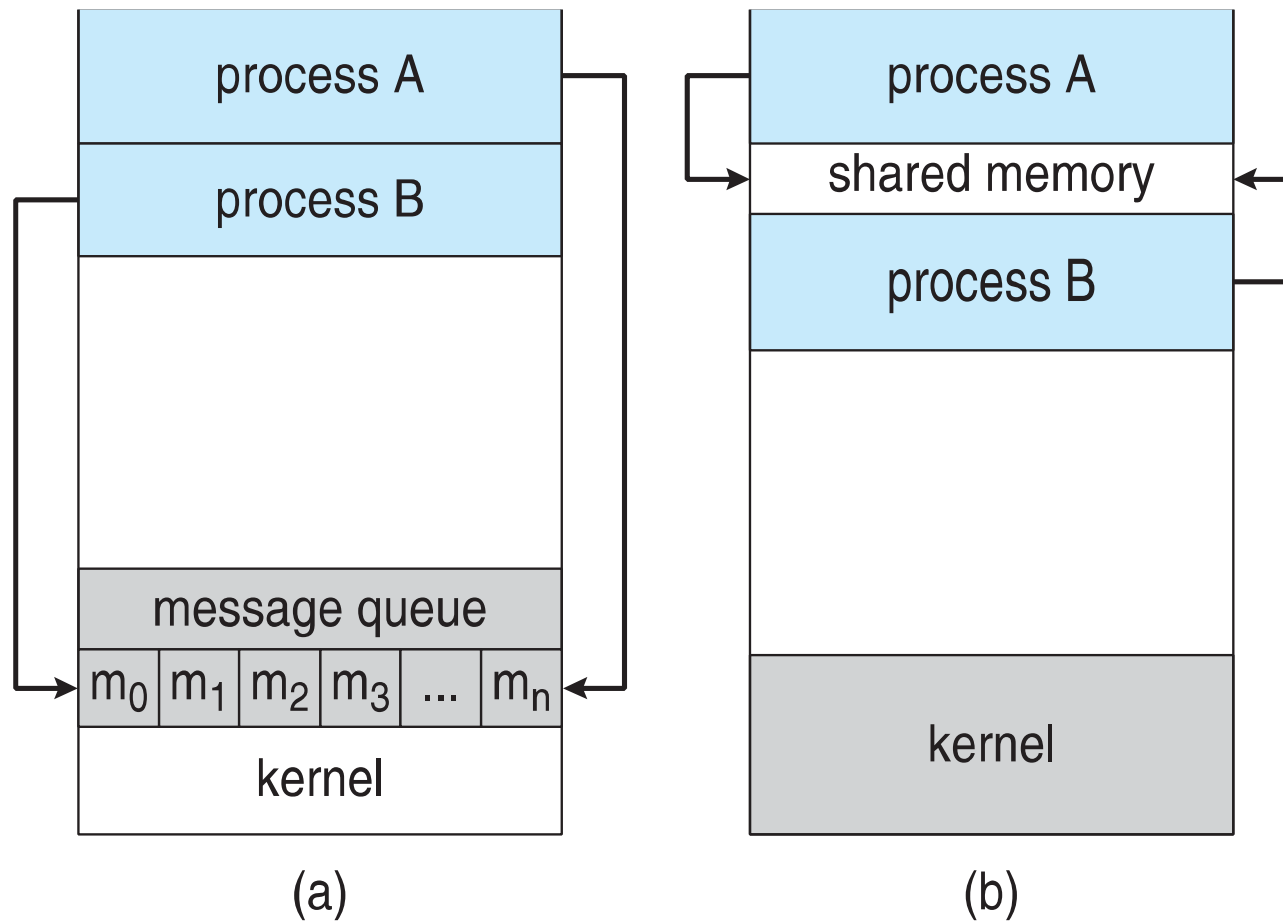
- Process executes last statement and then asks the operating system to delete it using a system call.
  - Returns status data from child to parent
  - Process' resources are de-allocated by operating system
- Parent may terminate the execution of children processes using a system call. Some reasons for doing so:
  - Child has exceeded allocated resources
  - Task assigned to child is no longer required
  - The parent is exiting

## 3.8 Inter-process Communication

- Processes within a system may be *independent* or *cooperating* when they need to share data
- There are two models of **inter-process communications (IPC)**
  - **Shared memory**
  - **Message passing**

# Inter-Process Communications Models

(a) Message passing. (b) shared memory.



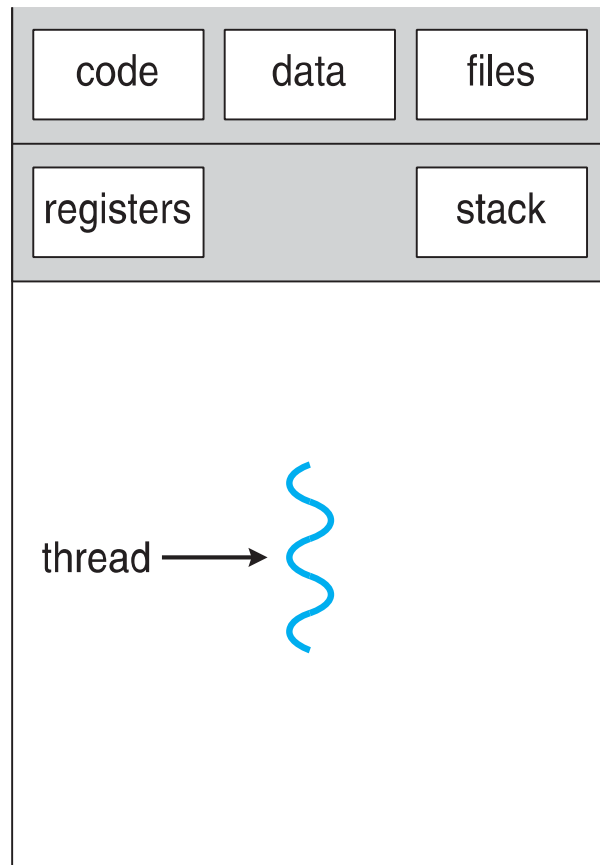
# **PART 2**

## **Threads**

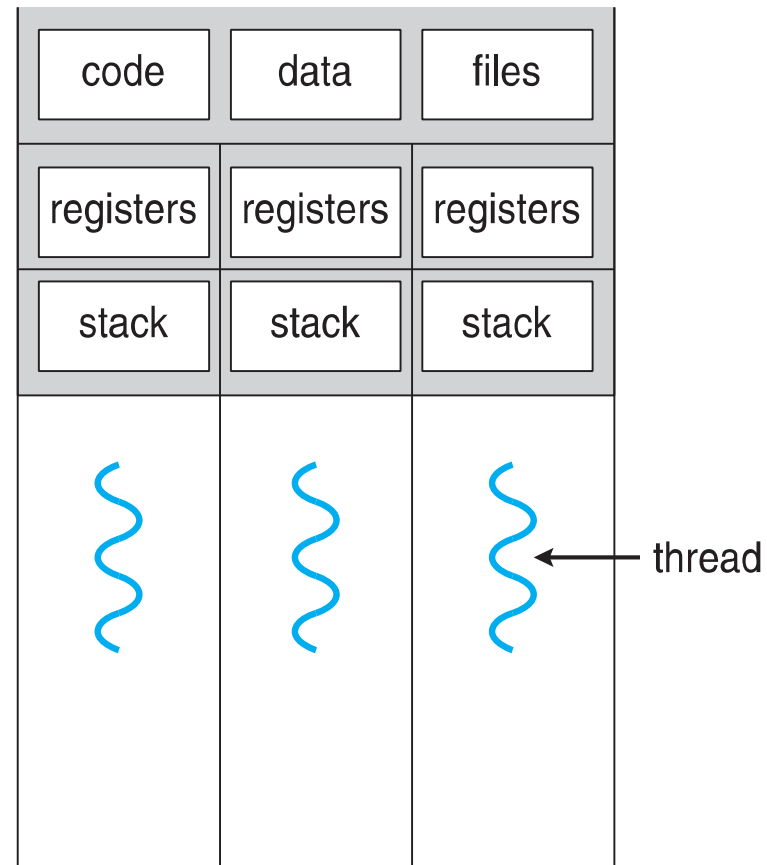
## 3.9 Thread Concept

- The thread is a component of the process and it is the smallest sequence of instructions that can be managed by the scheduler
- Multiple threads can exist within one process, executing concurrently and sharing resources such as memory.
- Implicit Threading where the creation and management of threads done by compilers rather than programmers.
- Most modern applications are multithreaded, so tasks with the application can be implemented by separate threads
  - Update display
  - Fetch data
  - Spell checking

# Single and Multithreaded Processes (not required in the exam)



single-threaded process



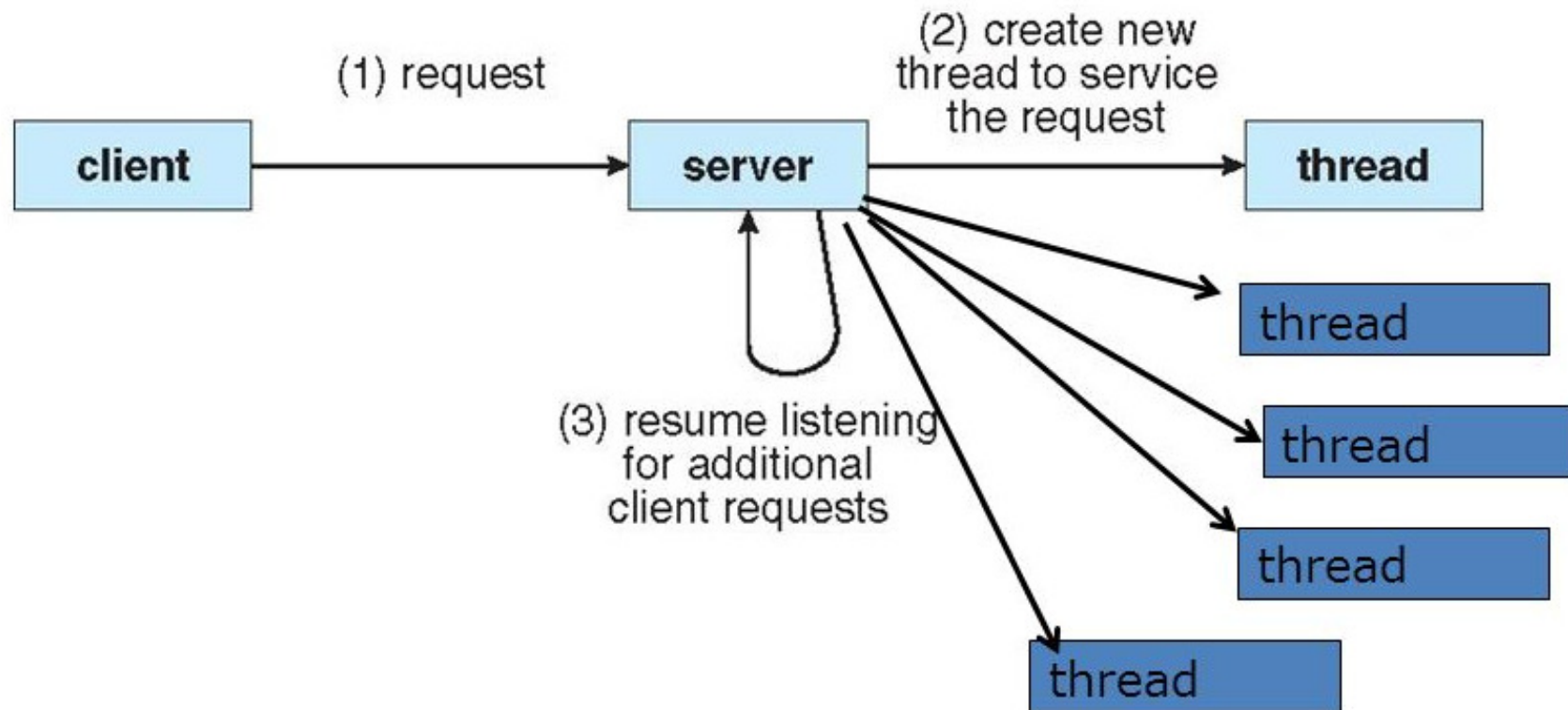
multithreaded process

# Multi-threaded Process Analogy





## 3.10 Multithreaded Server Architecture Example

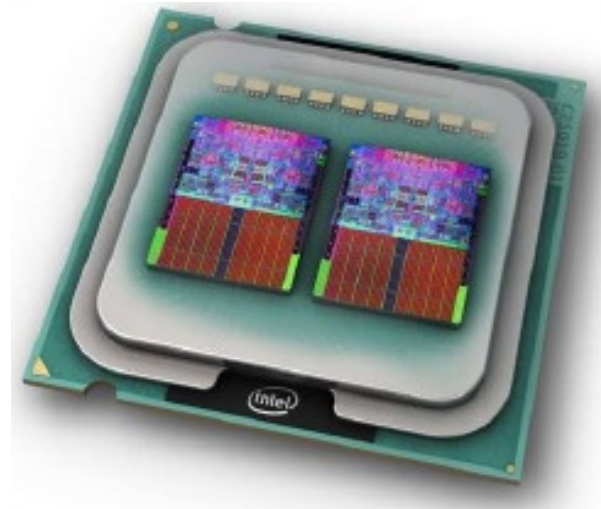


## 3.11 Multithreading Benefits

- **Responsiveness** – may allow continued execution if part of process is blocked, especially important for user interfaces
- **Resource Sharing** – threads share resources of process, easier than shared memory or message passing
- **Economy** – cheaper than process creation, thread switching lower overhead than context switching
- **Scalability** – process can take advantage of multiprocessor architectures

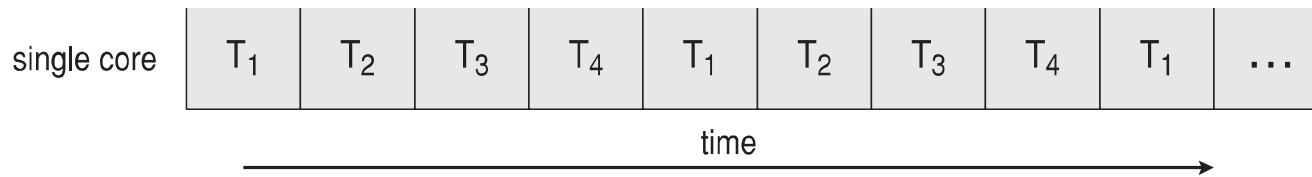
## 3.12 Multi-Processor Systems

- The systems can have single processor or multiple processors
- A system can have independent CPUs in single motherboard
- A multi-core processor is one which combines two or more independent processors into a single chip.

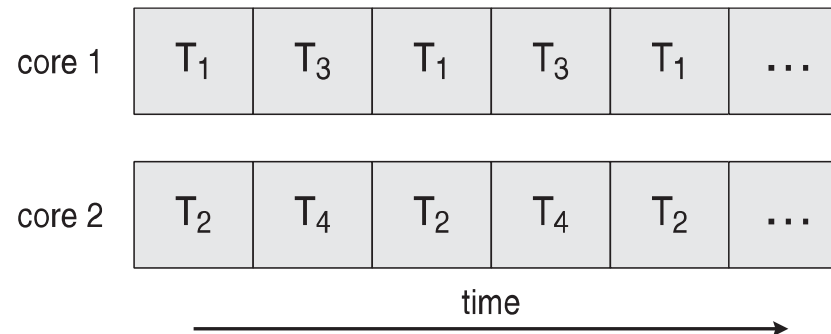


## 3.13 Concurrency vs. Parallelism

- **Concurrency** supports more than one task making progress, this can be implemented by a Single processor / core with a scheduler.



- **Parallelism** implies a system can perform more than one task simultaneously on multi-core system



## 3.14 Amdahl's Law

- This law Identifies performance gains from adding additional cores to an application that has both serial and parallel components

- $P$  is parallel portion

- $S$  is serial portion

$$speedup = \frac{1}{S + \frac{(1-S)}{N}}$$

$$S = 1 - P$$

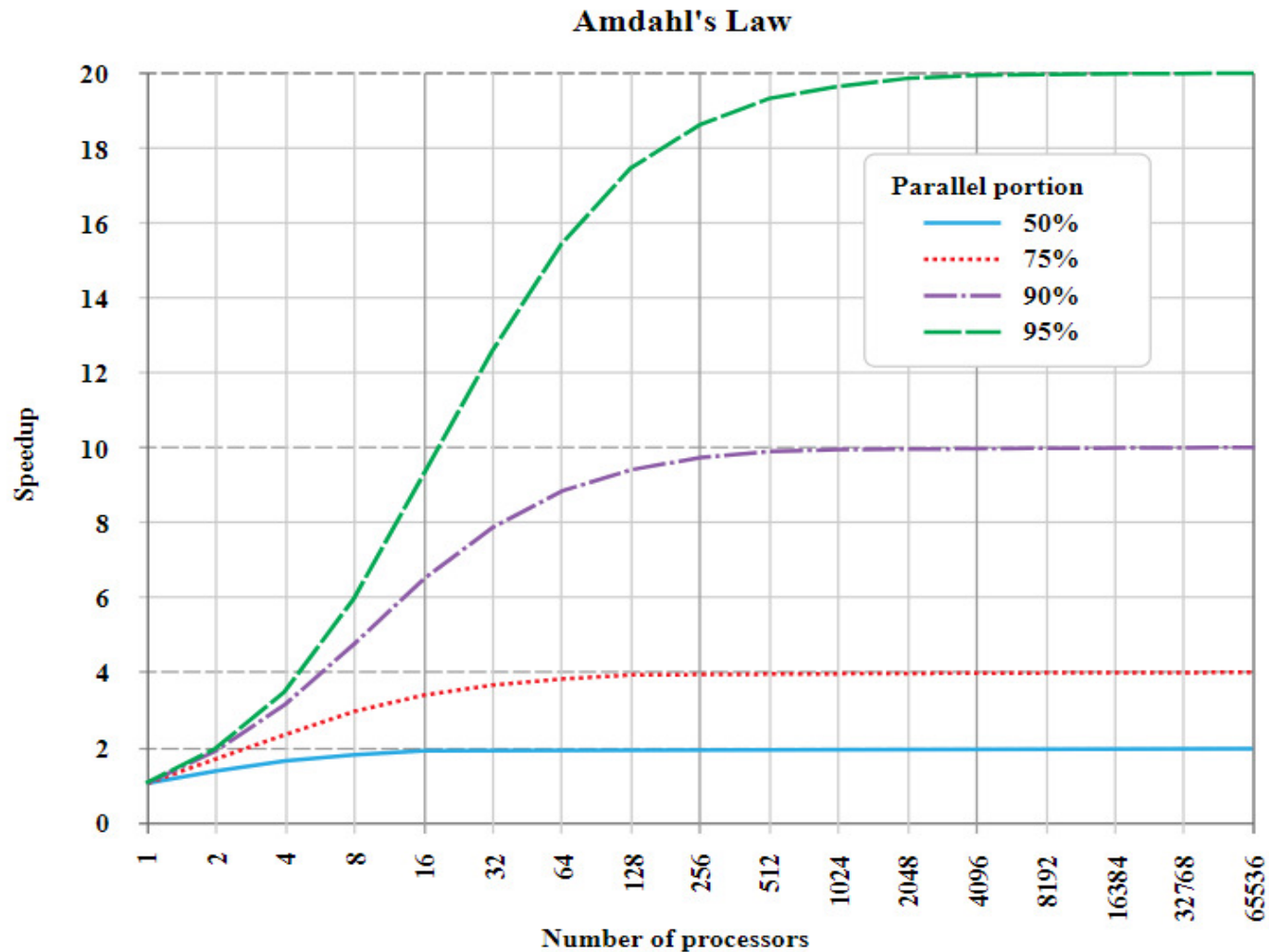
- $N$  processing cores

- As  $N$  approaches infinity, speedup approaches  $1 / S$

- **Serial portion of an application is limiting the performance gained by adding additional cores**

- Adding more processors leads to successively smaller returns in terms of speedup

# Amdahl's Law Graph (not required in the exam)



## Amdahl's Law Example

Q\ Using Amdahl's Law, calculate the speed up factor for moving from single processor to four processors with an algorithm that has %80 parallel part.

Answer\ Amdahl's Law state that:

$$speedup = \frac{1}{S + \frac{(1-S)}{N}}$$

$$N = 4$$

S = Serial Part

P = Parallel Part

$$S = 1 - P = 1 - 0.8 = 0.2$$

$$Speedup = \frac{1}{\left[0.2 + \frac{(1-0.2)}{4}\right]} = 2.5$$